

# Atmospheric Noise Removal for FYST: Current Methods and ML Prospects

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# A novel sub-mm telescope: 2025

The Fred Young Submillimeter Telescope (FYST): wide-field, 6-m aperture sub-mm telescope.

Site location: at 5600 meters on Cerro Chajnantor in northern Chile.

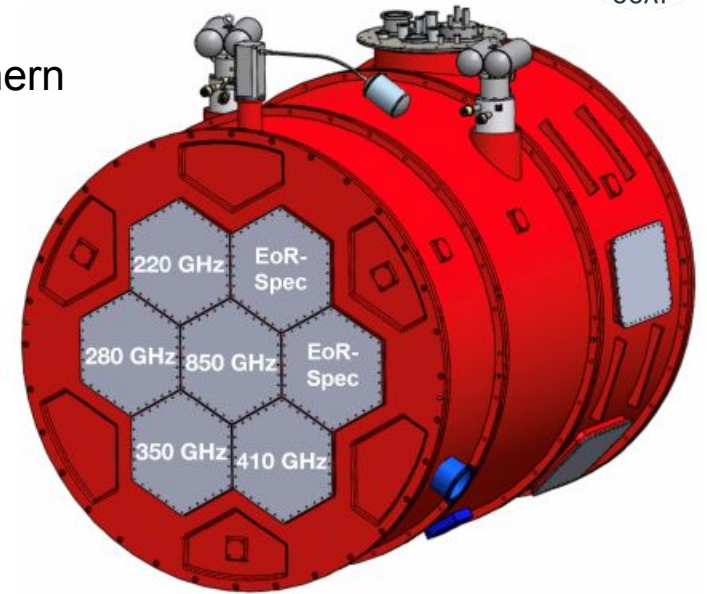
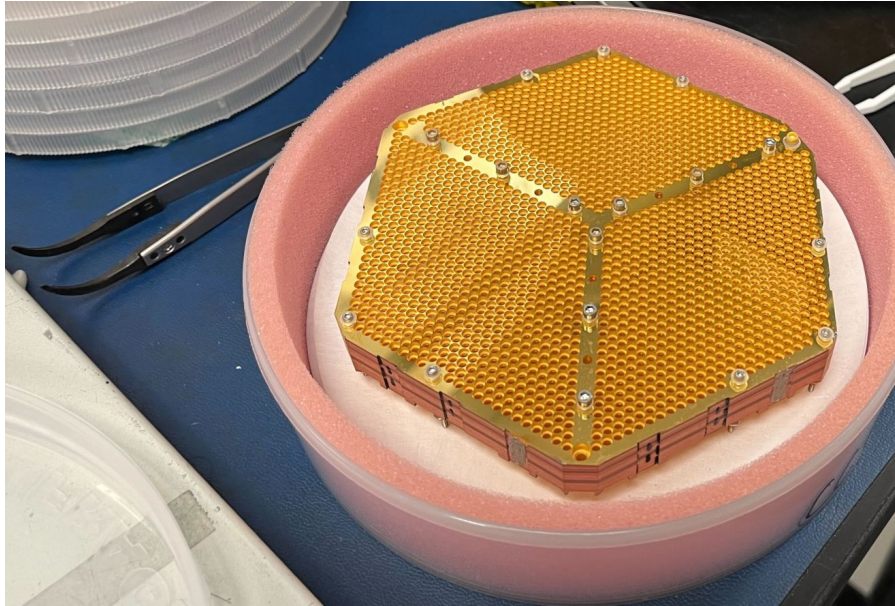


Fig above: FYST model at Cerro Chajnantor ([www.ccatobservatory.org](http://www.ccatobservatory.org))

Fig below: Prime-Cam instrument design with the seven instrument modules (Vavagiakis+2018)

# Under development : FYST Detector Arrays



~ 3500 detectors per array times x3 ;  
400Hz sampling rate  
⇒ Big data volume

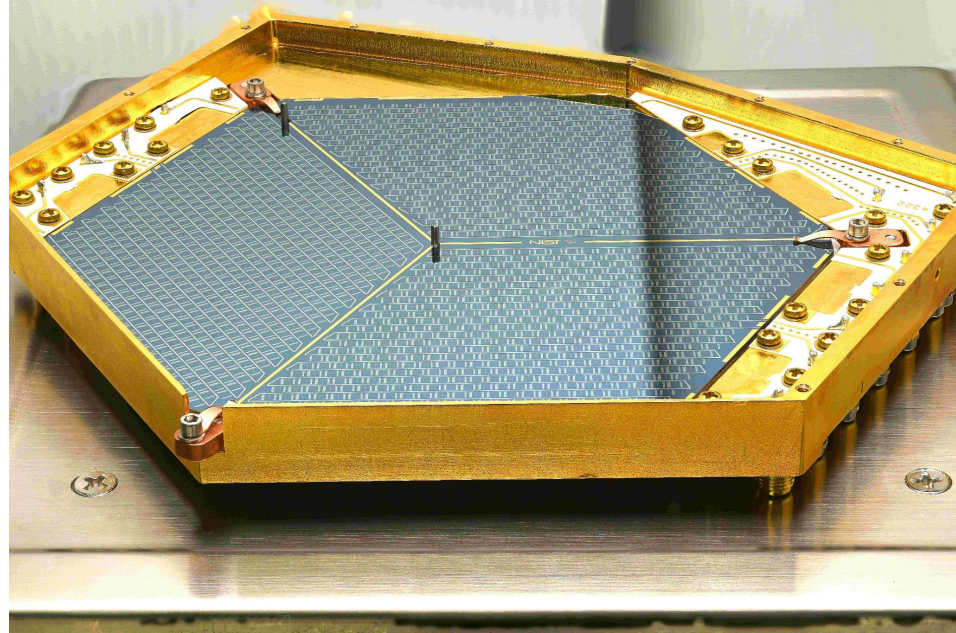


Fig Credit: Silicon feedhorn package, and 280GHz aluminum array (Cody Duell, Jordan Wheeler)

# Correlated Atmospheric Noise is a Challenge

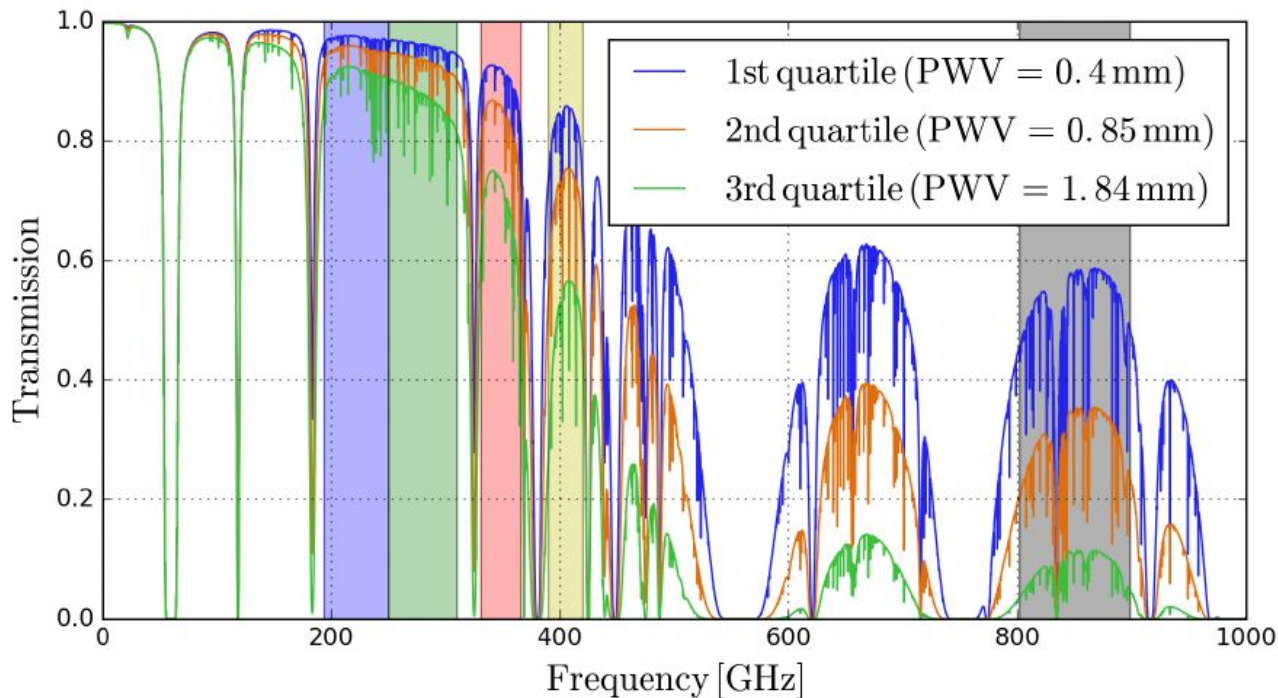


Fig left: Atmospheric transmission spectra for FYST Site (Choi et al 2020)

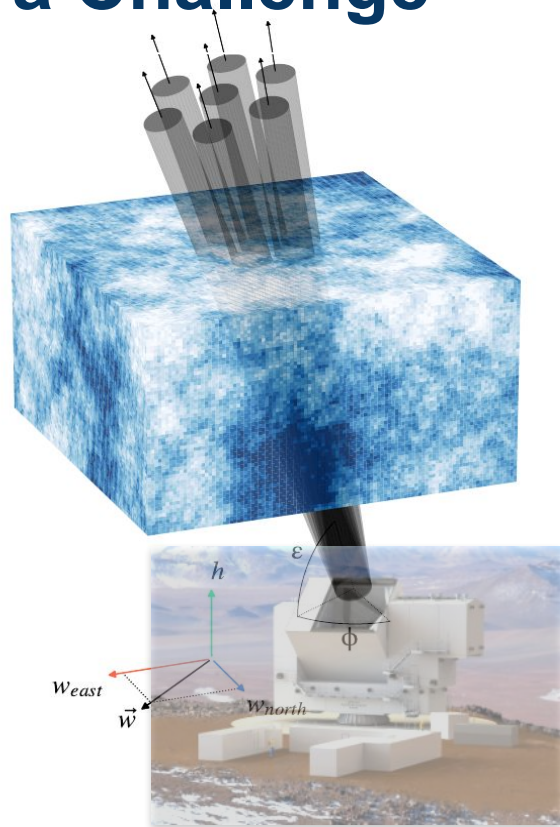


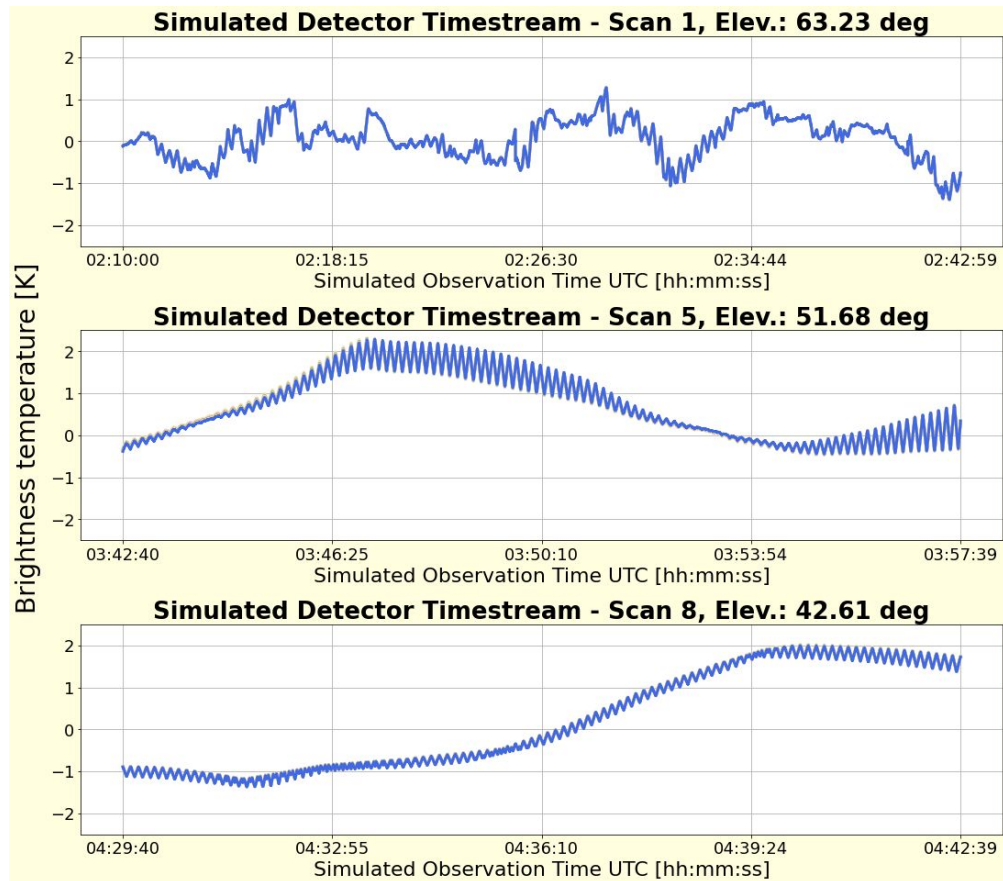
Fig right: Array of detectors observing through inhomogeneous atmosphere (Morris+2022) ; Adapted with FYST model

# Goal: Removing low-frequency Correlated Noise

We want to remove the correlated noise component, while retaining the underlying cosmological signal

$$d_v(t) = \langle d_v \rangle P_{cel} \Delta s_{science}^v + n_{white}(t) + n_{corr}(t)$$

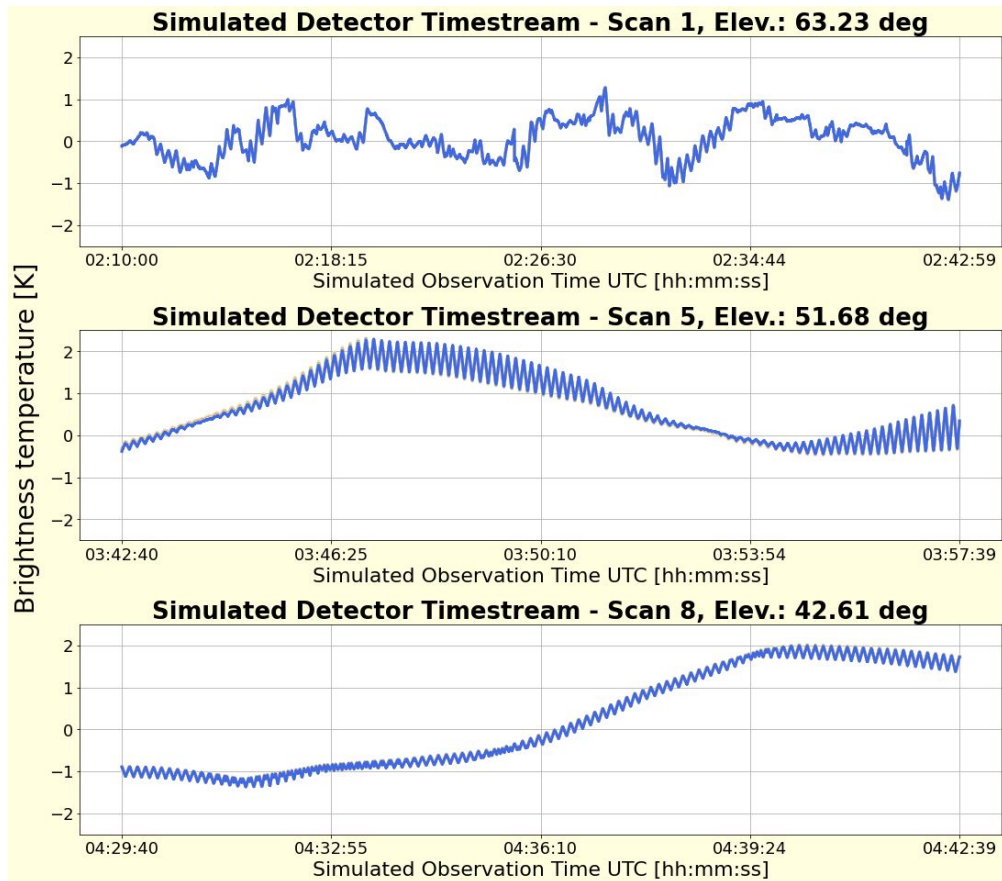
Detector Timestreams /  
Time-ordered Data (TOD)



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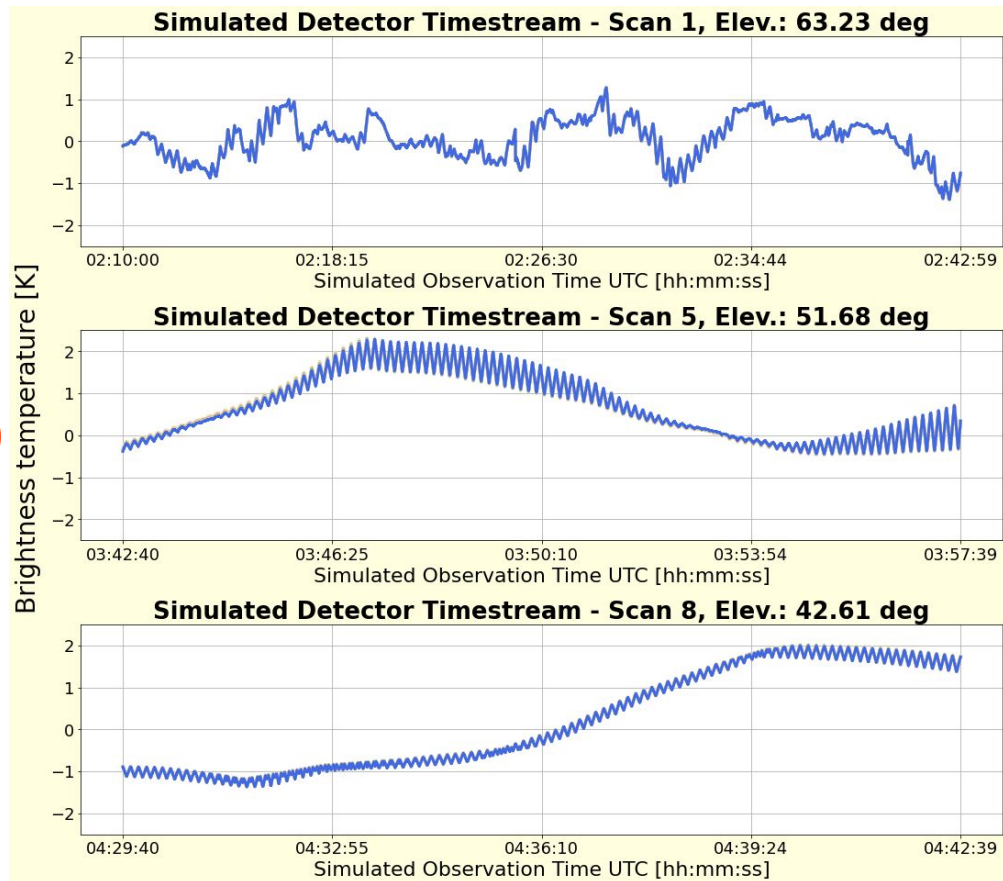


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The equation shows the detector output  $d_v(t)$  as a sum of the expected signal and two noise components. The terms  $n_{white}(t)$  and  $n_{corr}(t)$  are circled in orange and red respectively, indicating the focus of the noise removal process.

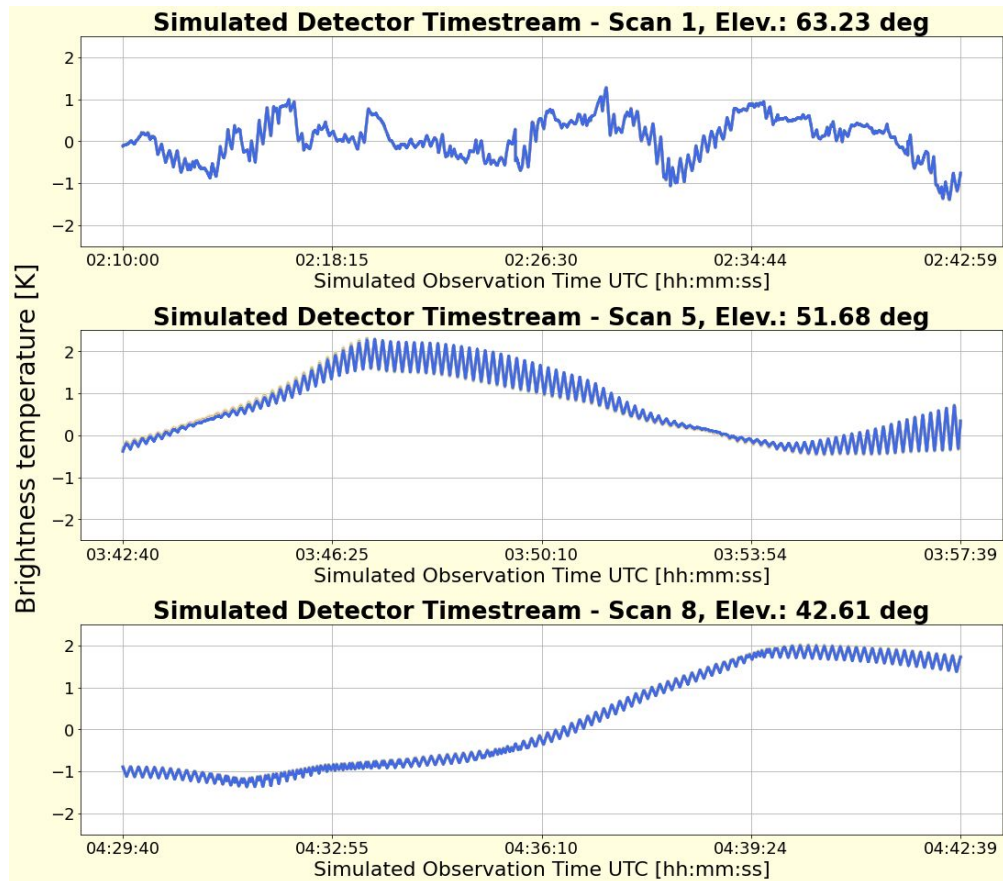


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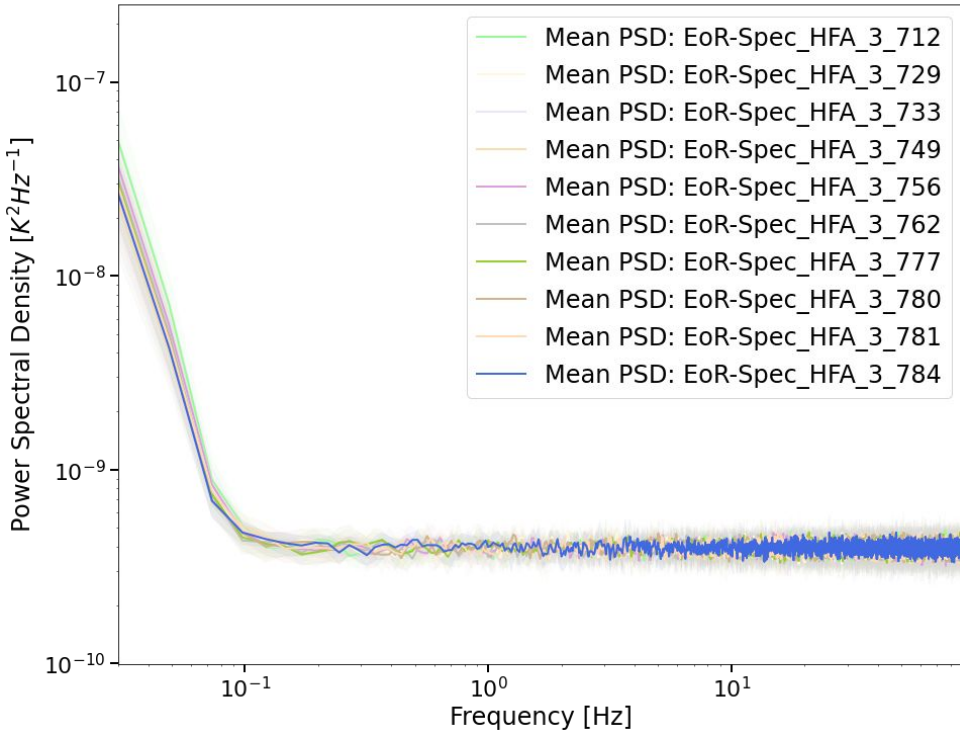
Data reduction includes:

- Data selection
- Detrending
- Filtering : Polynomial and Fourier space
- Principal Component Analysis (PCA)
- Flagging operations
- Map-making from Timestream





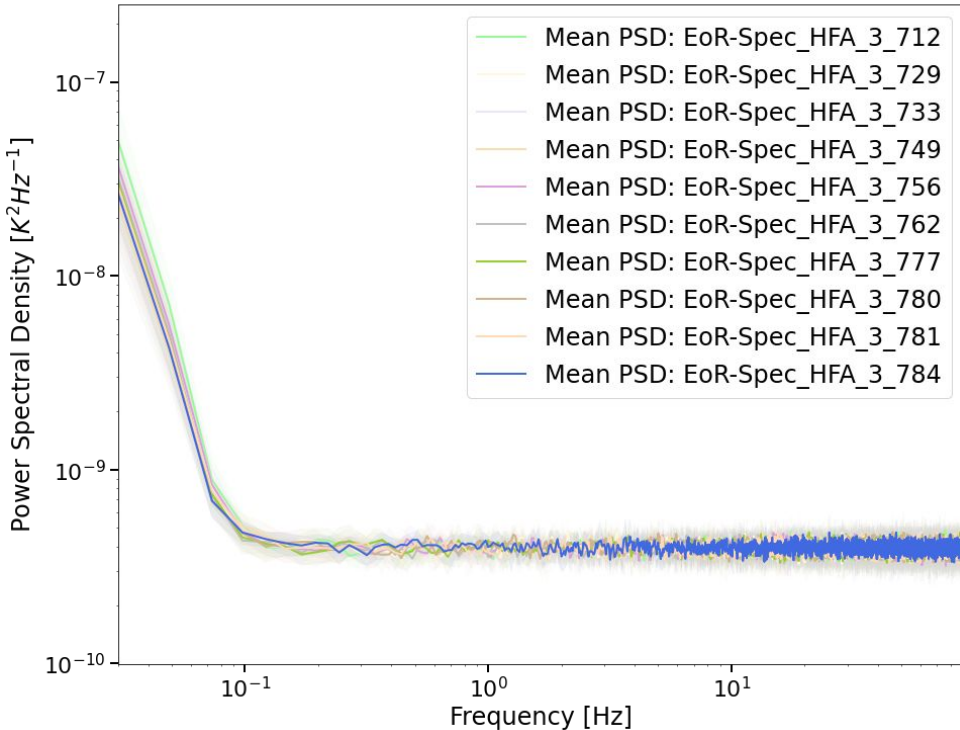
### Mean PSD of Timestream with Instrument noise



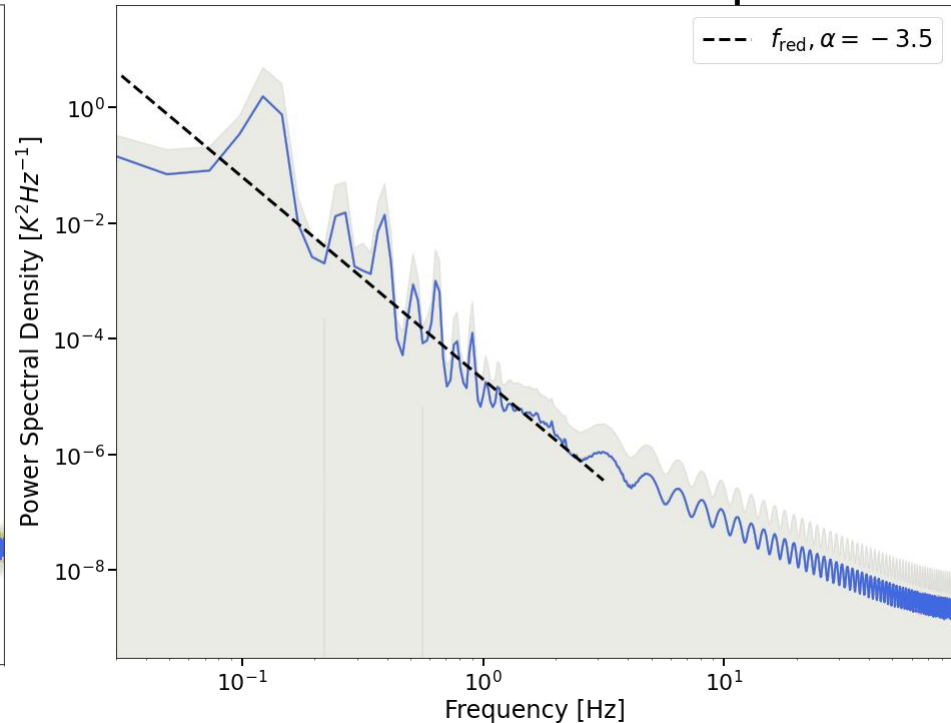
# Power Spectral Density: Atmosphere introduces 1/f Noise

$$N(f) = \sigma_0^2 \left( 1 + \left( \frac{f}{f_{\text{knee}}} \right)^\alpha \right)$$

## Mean PSD of Timestream with Instrument noise

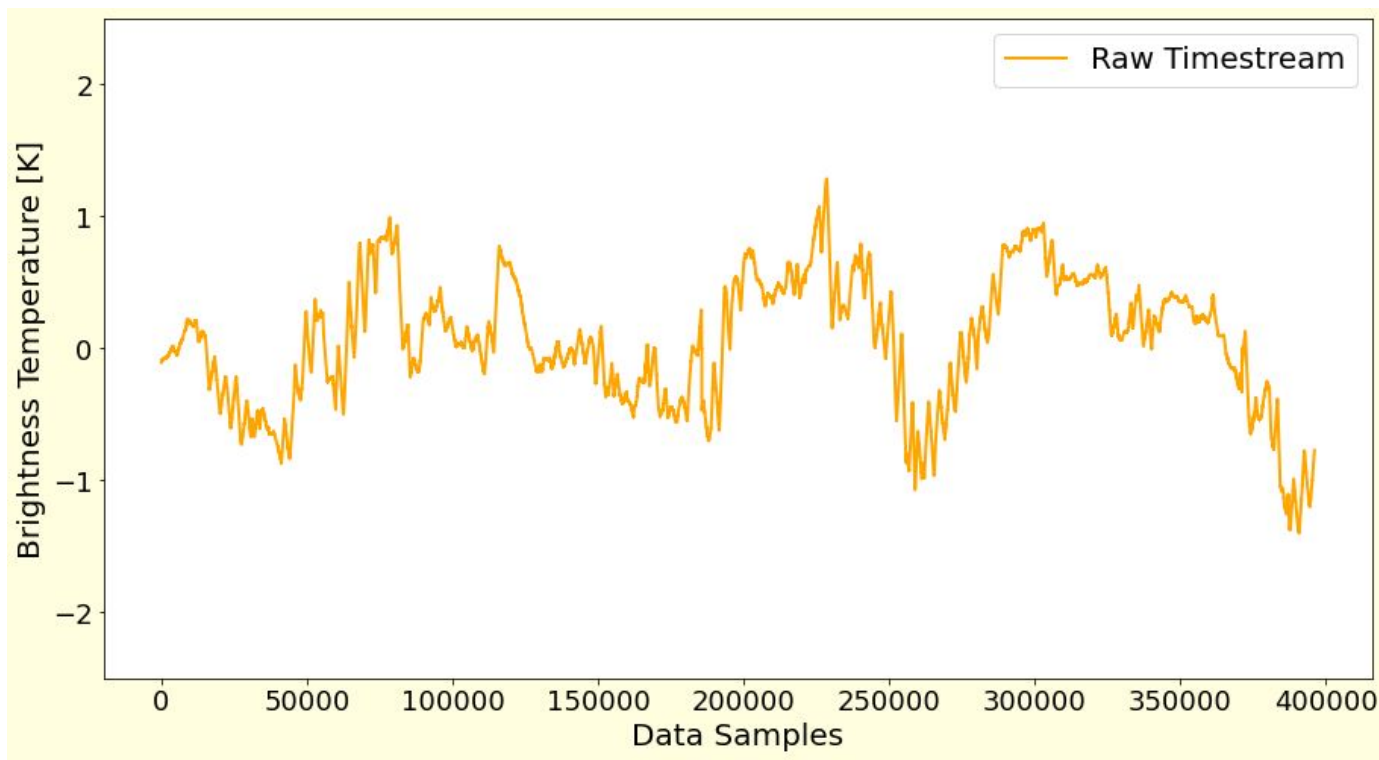


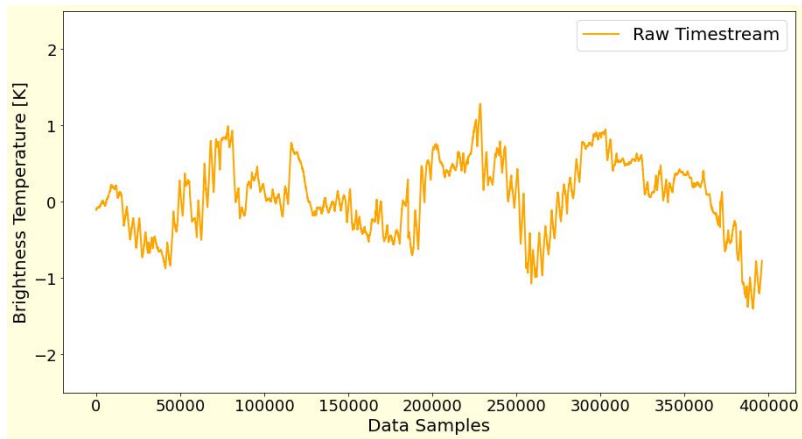
## Mean PSD of Timestream with Atmospheric noise



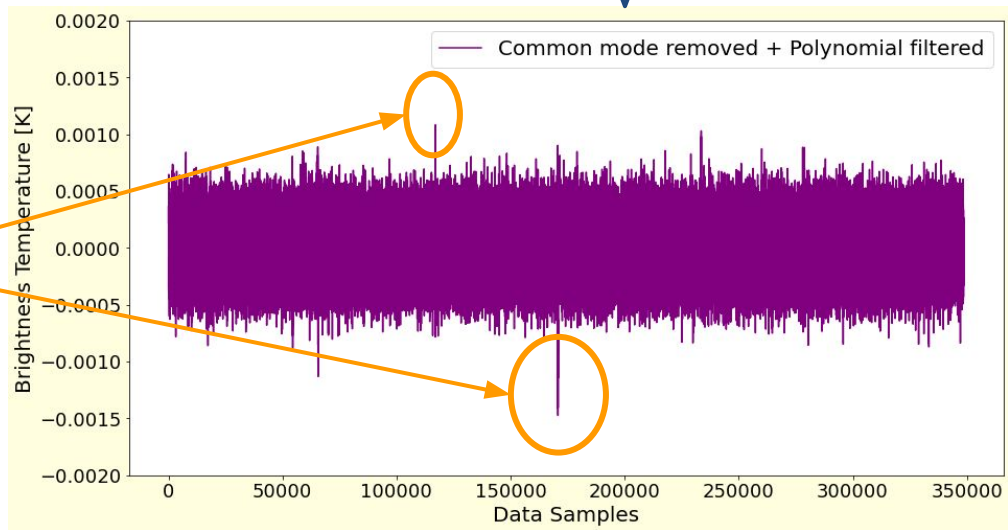
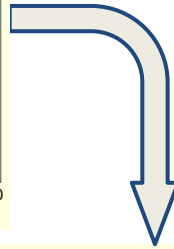
# Data-processing for removing Atmospheric Noise

Data:  
Detector  
timestream to be  
processed for  
removing trends



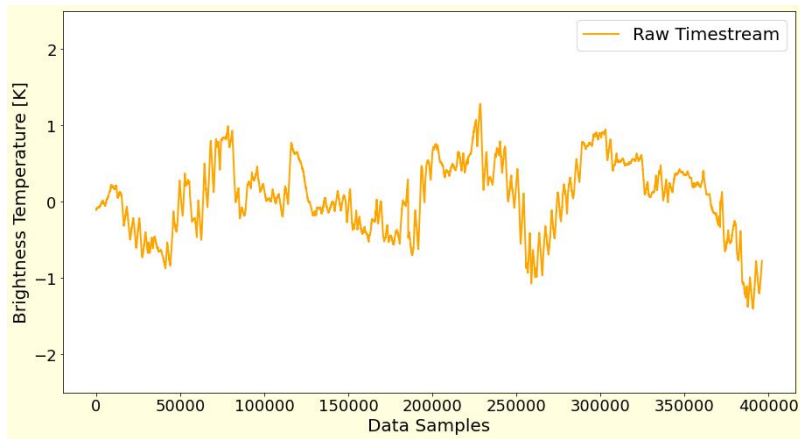


**Step 1:** Common mode removed from all detectors  
**Step 2:** 0<sup>th</sup> Order Polynomial subtracted

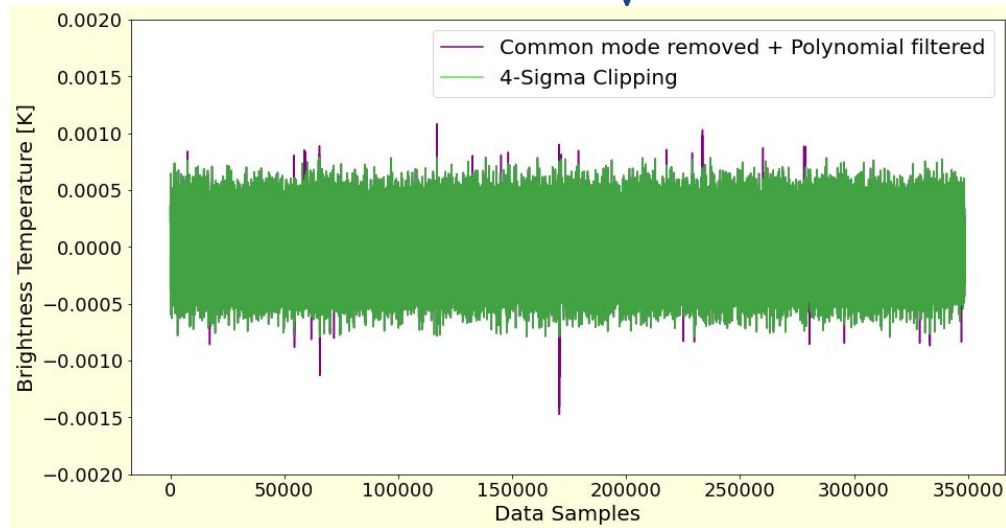


Few data-samples are poorly behaved

**Time-domain analysis**

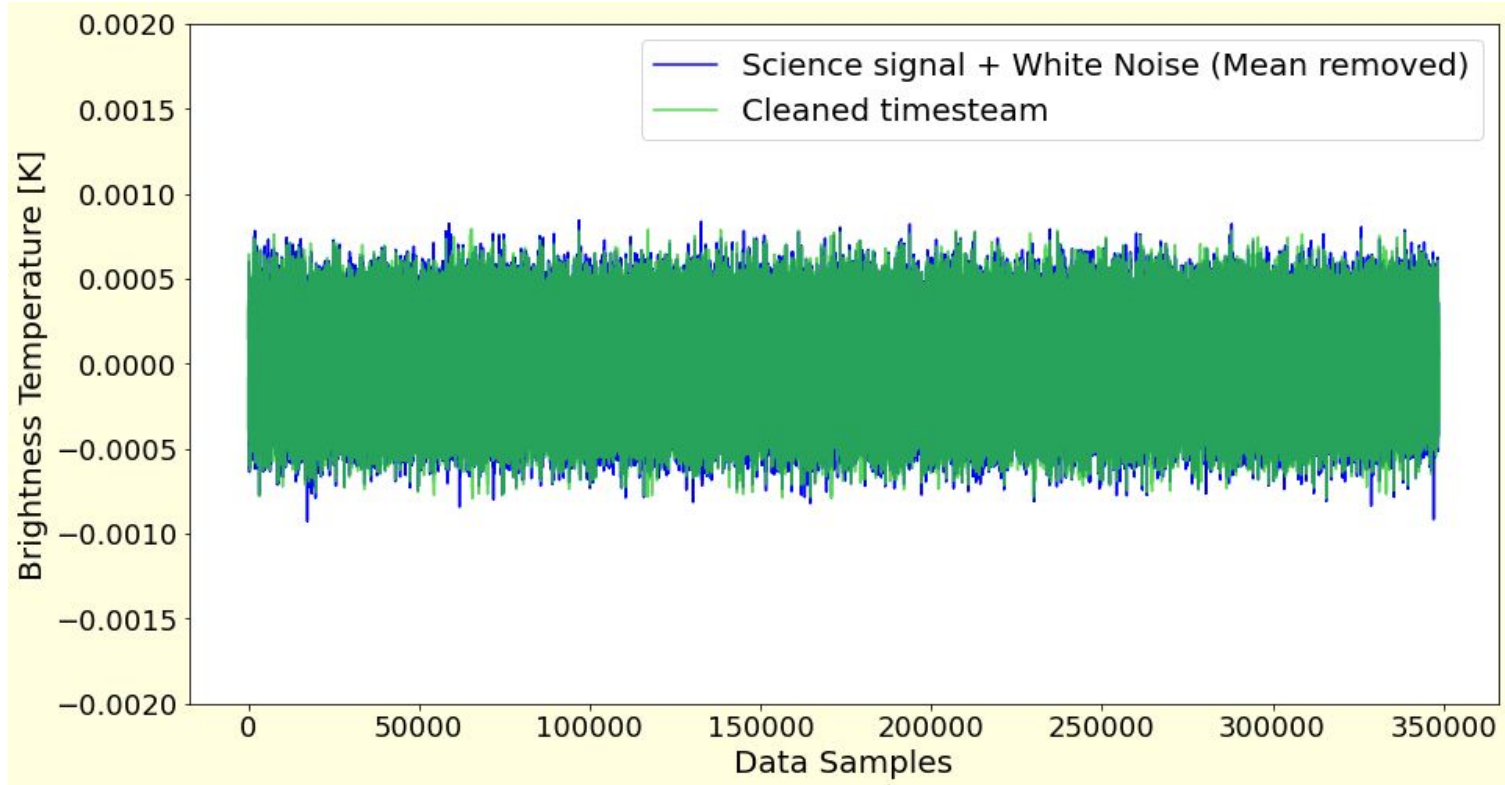


- Step 1:** Common mode removed from all detectors
- Step 2:** 0<sup>th</sup> Order Polynomial subtracted
- Step 3:** Excluding extreme statistical outliers (4-sigma clip)

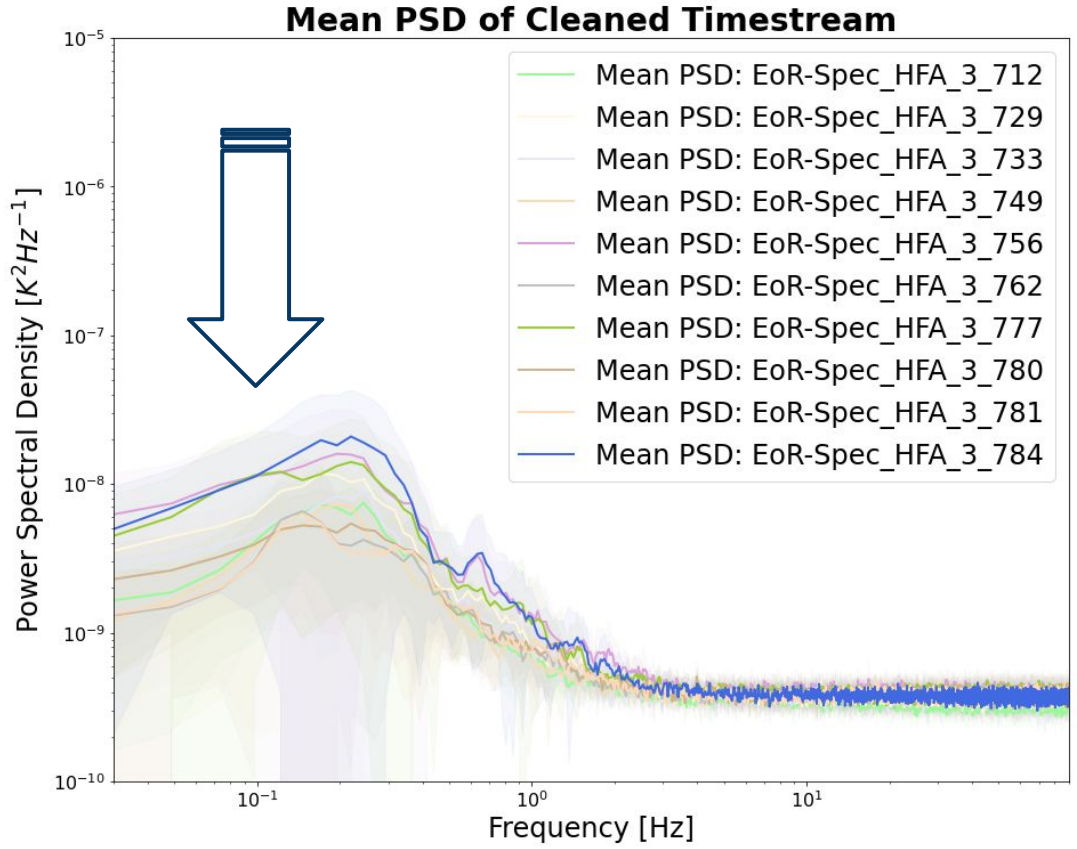
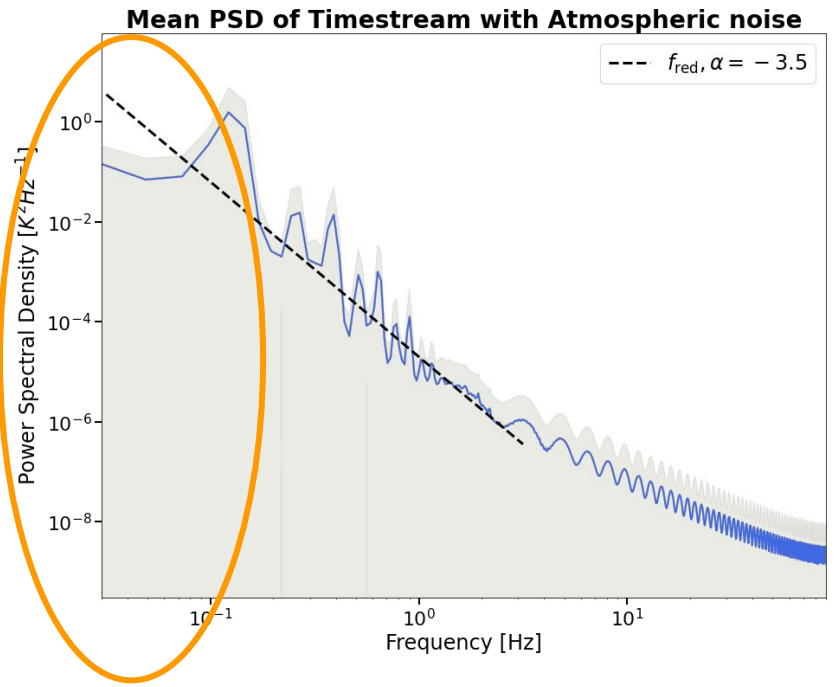


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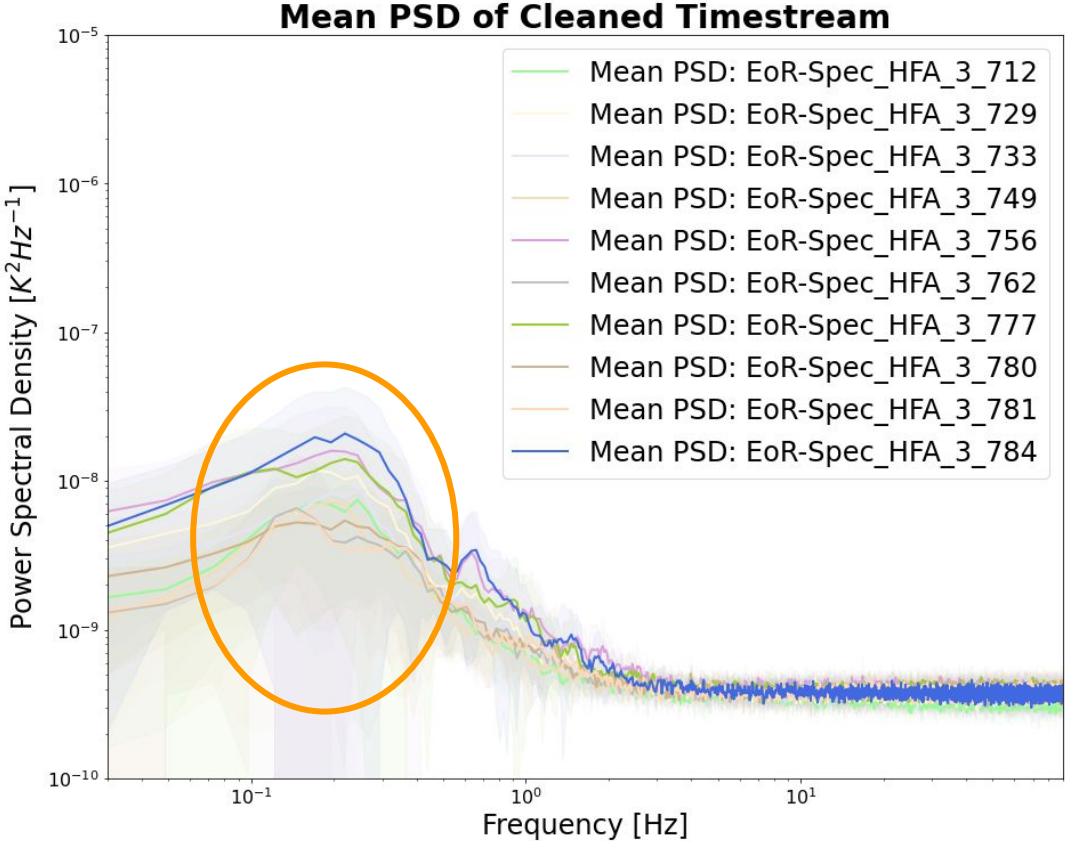
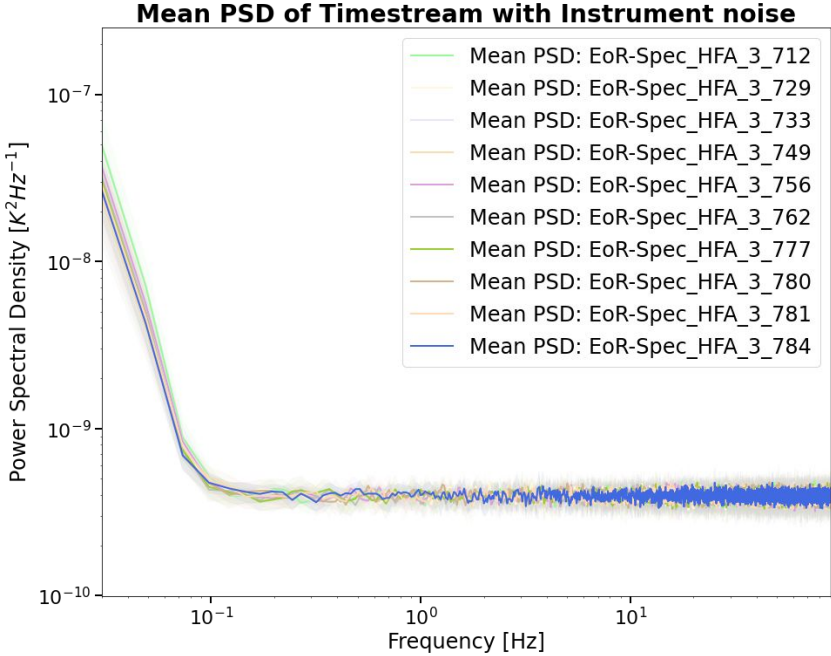
# Timestream Cleaned to White Noise Level



# Power Spectral Density Comparison of Cleaned Timestream



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# Can ML methods contribute to current data reduction techniques?

- Convolutional Neural Networks (CNNs)
  - Layered, hierarchical architectures for spatial/temporal pattern recognition.
  - Adaptability in identifying and reducing diverse noise components through encoding-decoding structures.
- Gaussian Process Regression (GPR)
  - non-parametric, Bayesian approach to model and predict time-series data.
  - modeling complex noise structures
- Monitoring Data Quality
  - Outlier Detection: Leveraging ML for identification of anomalies in detector timestreams.
  - Data Selection and Cuts

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