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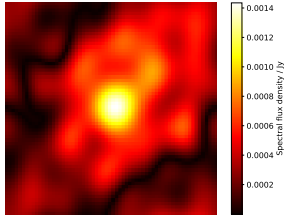
## A Neural Network Architecture For Radio Interferometric Imaging

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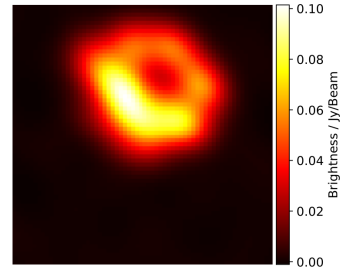
Stefan Fröse

22.10.2021

## Goal



Neural Network



# What is Radio Astronomy?

## Radio Astronomy

- Ground-based telescopes
- Wavelength: mm to m
- **Problem:** Resolution is limited by Rayleigh criterion

$$\begin{aligned}\alpha &= 1.22 \frac{\lambda}{D} \\ &= 1.22 \frac{1 \text{ mm}}{25 \text{ m}} \\ &\approx 10''\end{aligned}$$

**Solution?**



Credit: NRAO/AUI/NSF

## Radio Interferometry

- Correlate multiple telescopes pairwise
- Resolution depends on baseline  
( $\alpha = 25 \mu''$ )
- Number of baselines  $\frac{n^2-n}{2}$  (28@EHT)

### But:

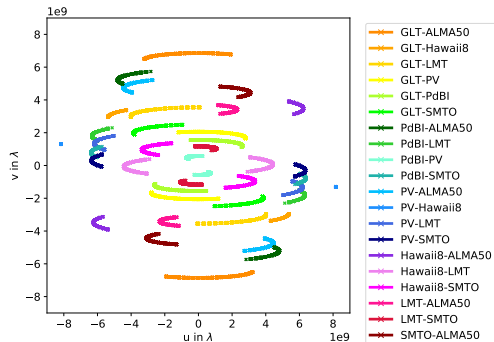
- Telescopes measure Fourier transformed distribution



Credit: NRAO/AUI/NSF

## Radio Measurement

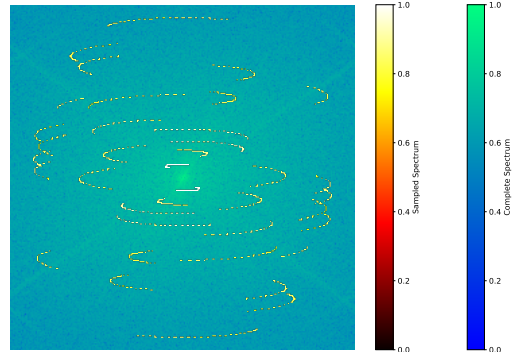
- Observe source  $\mathbf{s}$
- Baseline = projected distance  
⇒ Array as it can be seen by  $\mathbf{s}$
- Baselines change due to earth rotation
- Every telescope pair samples one point from Fourier spectrum at time  $t$



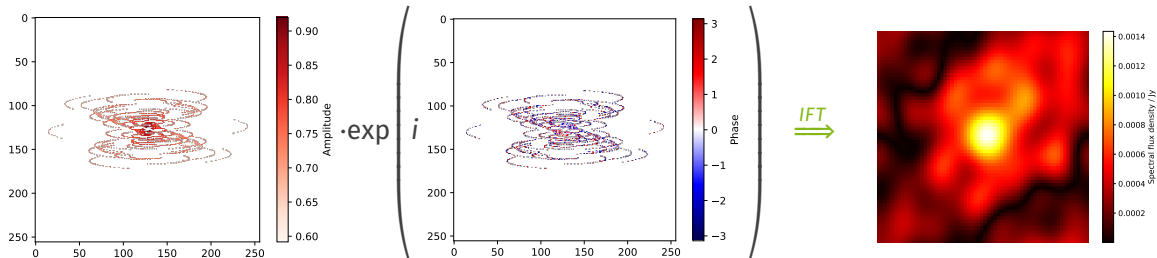
## Radio Measurement

- Sampled complex values  $a + ib$
- Can be expressed as  $A \exp(i\phi)$
- Amplitude image
- Phase image

⇒ Inverse Fourier Transform



## Radio Measurement



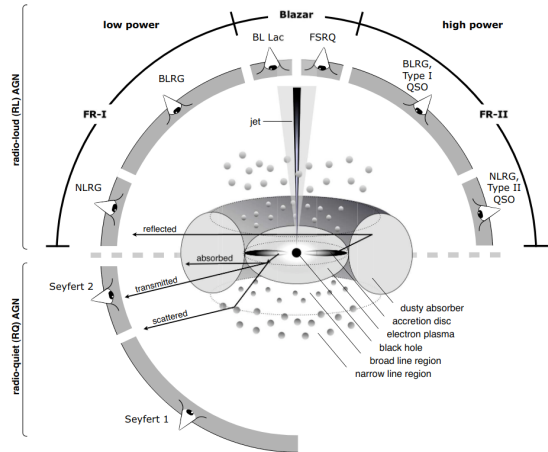
⇒ Dirty Map



# Sources to Reconstruct?

## Sources

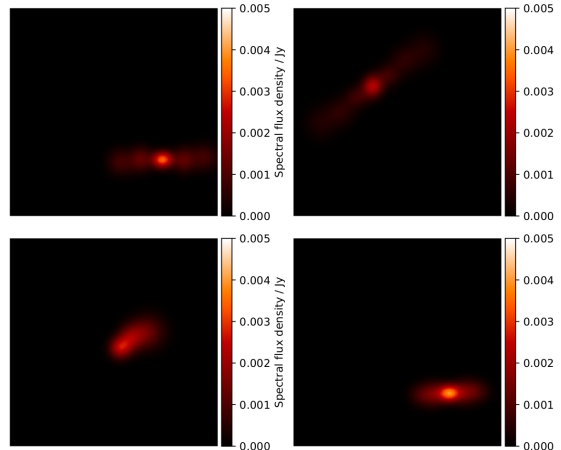
- Active Galactic Nucleus (AGN)
- Found in central region of galaxy
- Black hole as central engine → **EHT**
- Radio-loud AGNs have a jet → **MOJAVE**  
⇒ **Simulate jets and black holes**



Volker Beckmann and Chris R. Shrader. Active Galactic Nuclei. Wiley-VCH, 2012

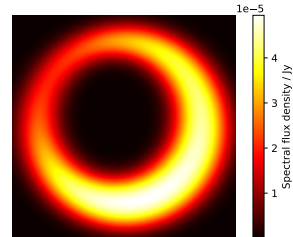
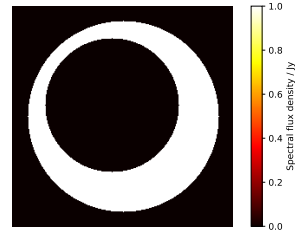
## Sources - Jet simulation

- **Motivation:** Kinematic jet analysis identifies components as Gaussians
- Generate random Gaussians along x-axis with small offsets
- $\mathbb{R}^3$  rotation and projection on xy-plane
- Normalize to 1 Jy



## Sources - Black hole simulation

- **Motivation:** Doppler beaming and gravitational lensing leads to crescent-like BHs  
→ **Geometric crescent model**
- Generate two circles
- Convolution of difference with asymmetric Gaussian
- Normalize to 1 Jy

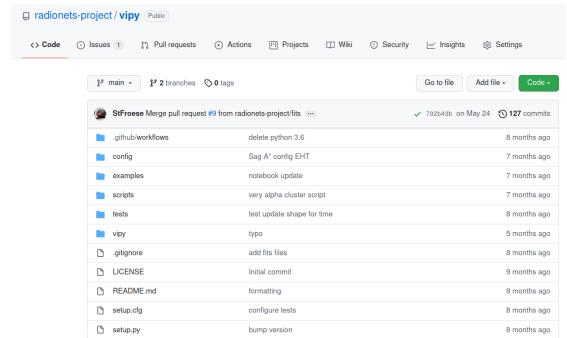


# vipy - A RIME simulation software

## vipy - A RIME simulation software

- Simulates measurement of custom sky distribution
- Based on Radio Interferometric Measurement Equation (**RIME**)
- Generates commonly used .fits file (AIPS memo 117)
- Available as open source software to the radio community

⇒ Why do I need this?



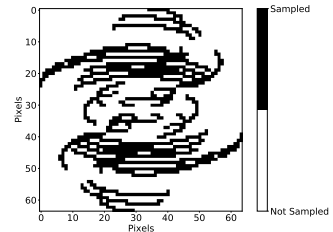
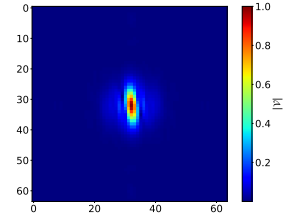
## Simple simulation

- Fourier transform of truth
- Generate mask based on sampled points in (u,v)-plot
- Apply mask to image

### But:

- No telescope properties taken into account (Telescope Response, Antenna noise)
- No physical effects (Atmosphere, Polarization)

⇒ **Advanced Simulation with vipy**



## vipy - Simulation

$$V_{pq} = \iint_{lm} J_p(l, m) B(l, m) J_q^H(l, m) dl dm$$

- Radio Interferometer Measurement Equation **RIME**
  - Visibility of telescope pair  $pq$  depends on Matrices  $J_i$
  - $J_i$  Jones matrices → describe different physical effects
  - $J_i = \text{Baselineeffects} \cdot \text{Polarization} \cdot \text{Atmosphere} \cdot \text{Noise} \cdot \dots$
- ⇒ Choose Jones matrices & solve integral



# Neural Network Architectures

## Problem Definition

- **Goal:** Fill missing information
- Missing pixels are maximal corrupted pixels

### Similar Problem:

- Upscaling Low-Resolution to High-Resolution (HR) images
- First approach: Interpolation
- **Better:** Use Neural Network to predict HR images

⇒ **SRResNet**

bicubic



SRResNet

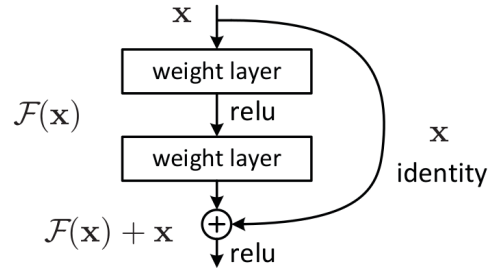


"Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network" C. Ledig et al., 2017 IEEE (CVPR), pp. 105-114

## Residual Learning

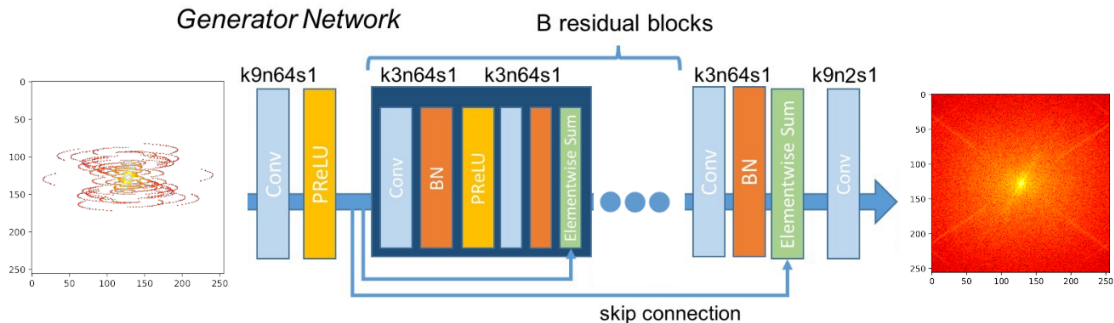
- Input  $x$ , Output  $y$
- Use of skip connections
- Gives residual approach
- NN has to learn underlying mapping function

$$F(x) = y - x$$



"Deep Residual Learning for Image Recognition", K. He et al., 2016 IEEE (CVPR), pp. 770-778

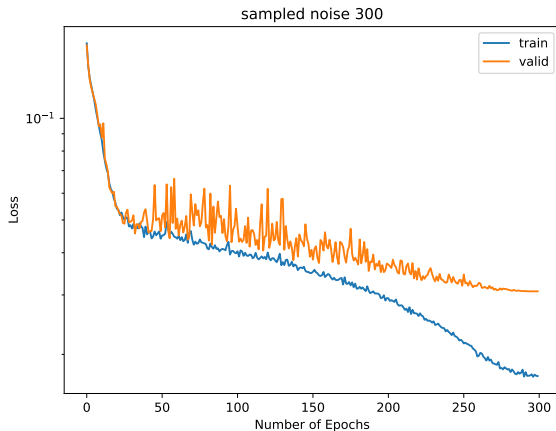
## SRResNet



"Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network" C. Ledig et al., 2017 IEEE (CVPR), pp. 105-114

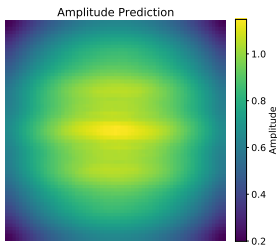
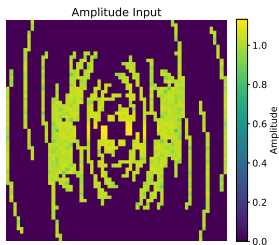
## SRResNet Training

- 50000 jet images (older simulation)
- $63 \times 63$  pixel
- L1 loss
- 300 epochs

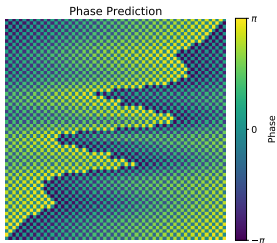
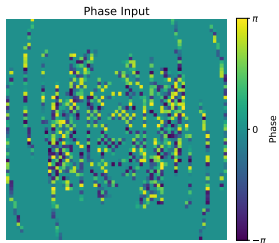


## SRResNet Results

Input

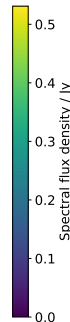
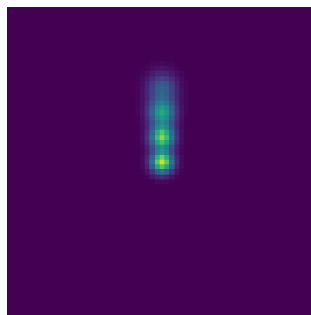
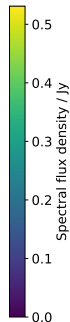
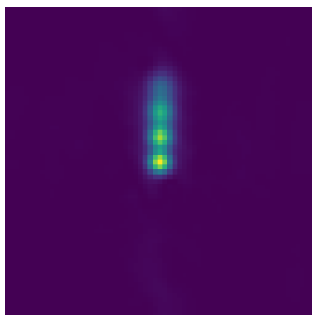


Prediction



## SRResNet Results

Predic-  
tion



Truth

⇒ Alternative: Clean dirty map

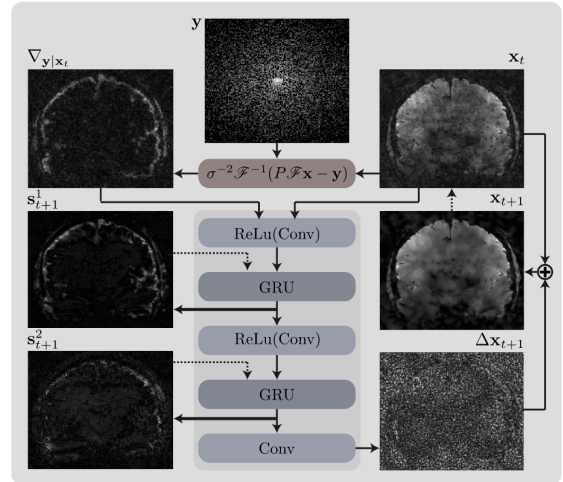
## RIM

- Recurrent Inference Machine (RIM) from MRI
- Solve inverse problems

$$I_{\text{Dirty}}(l, m) = F(S(u, v)V(u, v)) + n$$

- Iteratively clean dirty map

$$\mathbf{x}_{t+1} = \mathbf{x}_t + \Delta \mathbf{x}_{t+1} \quad (1)$$



K. Lønning et al. "Recurrent inference machines for accelerated MRI reconstruction." In: 2018.



## RIM Training

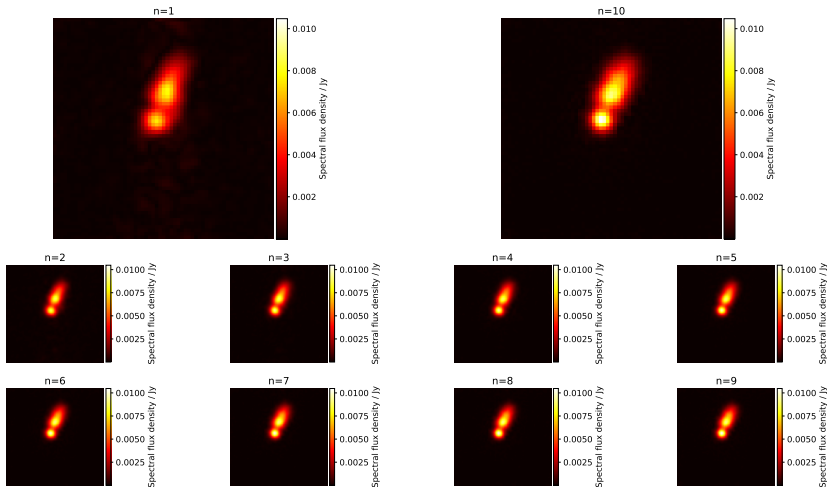
### jetRIM:

- 2400 images of jet simulations
- $63 \times 63$  px
- 10 inference iterations
- 300 epochs
- L1 loss

### bhRIM:

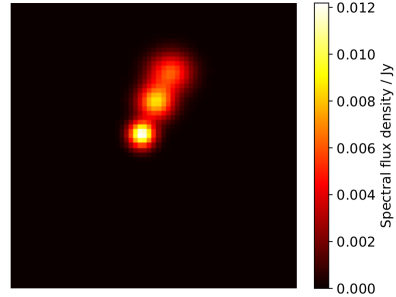
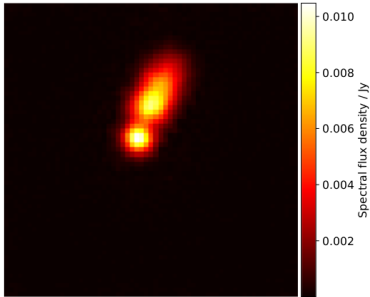
- 5000 images of black hole simulations
- $64 \times 64$  px
- 10 inference iterations
- 300 epochs
- L1 loss

jetRIM



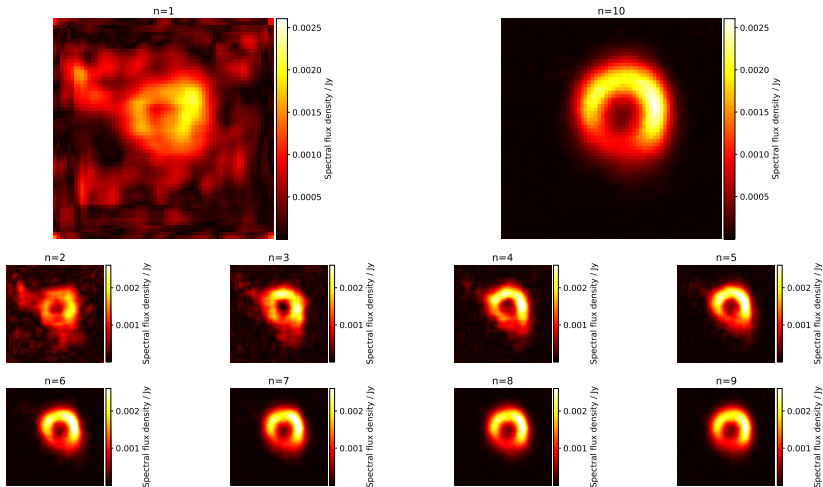
## jetRIM Results

Prediction



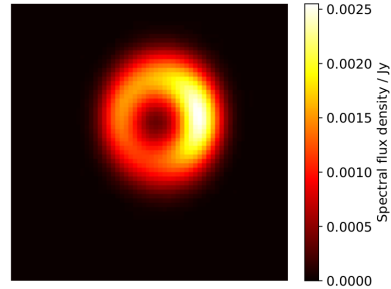
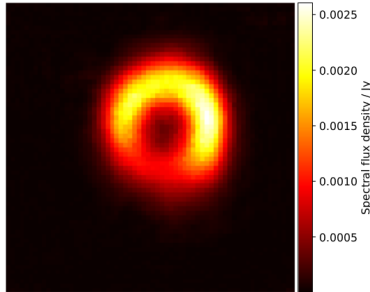
Truth

# jetRIM



## jetRIM Results

Prediction

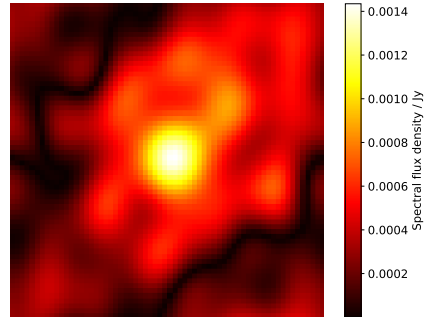


Truth

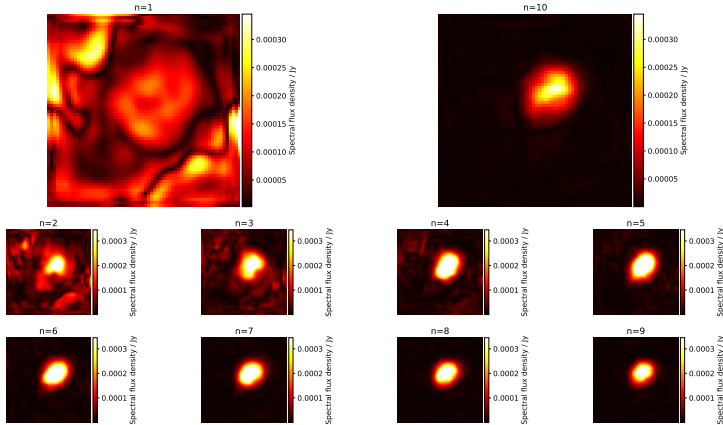
# M87 Black Hole

## M87 - Dirty Map

- EHT observation from 05.04.2017
- Self-calibration using DIFMAP
- Unknown total flux → RIM activations don't get triggered



## bhRIM - M87

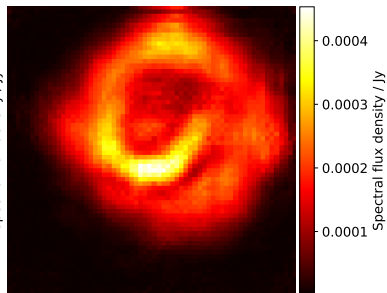
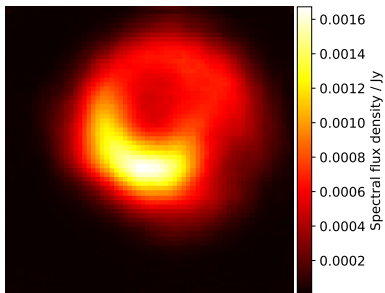


⇒ Multiply dirty map with scaling factor  $\alpha = 1 - 20$



## bhRIM - M87

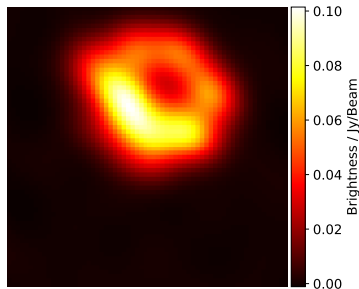
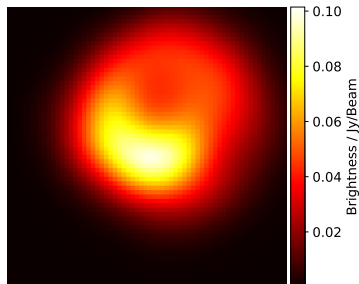
Mean



Standard  
Deviati-  
on

## bhRIM - M87

Predic-  
tion RIM



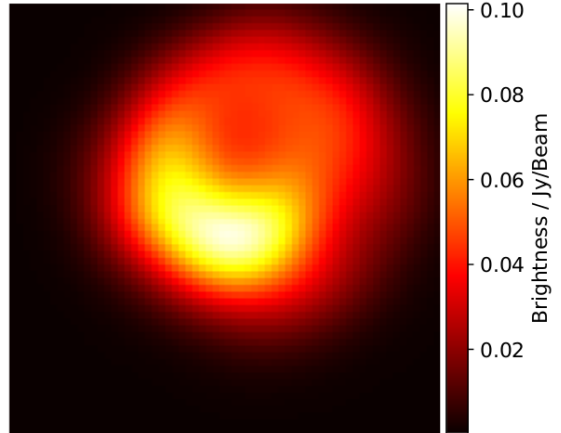
Results  
EHT

⇒ Further Investigation

# Outlook

## Outlook

- Enhancement of the vipy software  
→ Implementation of different Jones matrices
- Improvement of the RIM architecture (e.g. parallel convolutions)
- More versatile and larger training dataset
- Investigation of SKA sized images



Thank you!